

Expected Running Time of Hier. Coll. Det.

 Simultaneous traversal of two BVHs equals traversal of one bounding volume test tree (BVTT)















• The Cost formula:

$$T = N_V C_V + N_p C_p + N_u C_u + C_i$$

 $N_V, C_V =$ num. and avg. costs of BV overlap tests, resp. $N_p, C_p =$ num. and avg. costs of primitive intersection tests $N_u, C_u =$ num. and avg. costs of BV updates, resp. $C_i =$ initialization costs

- Worst-case: O(n²)
- Question: average case?
 - Clearly: $N_p \leq \frac{1}{2}N_V$ and $N_u \leq N_V$
- Task: determine average $N_v = \#$ nodes in the BVTT that are visited *on average*



Probability that child BVs overlap (on average):

$$p_{ij}^{(l)} := \Pr[A_i^{(l)} \cap B_j^{(l)} \neq \emptyset \mid A^{(l-1)} \cap B^{(l-1)} \neq \emptyset]$$

- Assumptions to simplify things:
 - Overlap δ of A and B along x axis is known
 - "BV diminishing factor" α_x : $a'_X = \alpha_X a_X, \ a'_y = \alpha_y a_y, \dots$
 - Boxes are of same order on same level, i.e.,

$$b_X = a_X, \ b'_X = a'_X, \ \dots$$











- Other child BV overlap probabilities
 - Similarly determine p₂₁, etc. ...
 - Turns out that all p_{ij} are equal, i.e., $p_{21} = p_{12} = p_{22} = \alpha_y \alpha_z$
- A lot depends on how many BV pairs on level I overlap along x axis
 - Some child BVs x-overlap by same amount as parent BVs
 - Some child BVs don't x-overlap any more
 - Some child BVs x-overlap by a smaller amount than parents





Overall expected number of nodes visited in BVTT:

$$\tilde{N}_{V}(n) = \sum_{l=1}^{\lg n} \tilde{N}_{V}^{(l)}(\delta, \alpha_{X}) \cdot \alpha_{Y}^{l} \cdot \alpha_{Z}^{l}$$

• Experimentally determined $\tilde{N}_{V}^{(I)}(\delta, \alpha_{X})$



