Prediction Correctness Value (PCV)

For every trajectory segment $t$ of each participant $u$, our classifier returns a probability $p(t, u)$. The PCV is the difference between the calculated probability of the correct participant $p_c(t)$ and the highest probability from any other participant $p_{\text{m}}(t)$.

$$\text{PCV}(t) = p_c(t) - \max_{u \neq c} p_u(t).$$

In case of a correct prediction, the PCV is positive. If the classifier predicted a wrong participant, the PCV will be negative. The greater the difference from the first to the second guess of the algorithm, the greater the absolute value of the PCV.

Datasets

We use two datasets from the 2015 BioEye competition [3]. Both contain data obtained from 153 participants, whose tasks were to read a poem, and to observe a randomly moving dot (not featured on this poster).

We thank Oliver Komogortsev for providing the used dataset.

Prediction Correctness Trajectory (PCT)

In Figure 3 the PCT is shown for all trajectory segments of a participant reading a poem. (a, b) show the test case, where the algorithms have not seen the data before. (c, d) show the training case. With this visualization it is visible that RF (left) is overfitting (it identifies every segment correctly in the training data (c) but not in the test case (a). RBFN performs similarly on the training (d) and on the test data (b). Beside other things, with this visualization, we can see that the outliers are correctly identified in the training data, while they are mistaken for a different participant by both classifiers in the testing cases. In contrast, eye movements in the region of the text are mostly correctly classified.

References


Visualizing Prediction Correctness of Eye Tracking Classifiers

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Classification via Eye Tracking Trajectories

Eye tracking data is often used for classification tasks. As example, we determine users based on their eye movements (see [1]). Our Method builds on the classification probabilities from fixations and saccades.

Segmentation: To divide the gaze trajectories into fixations and saccades, we implemented the simple Identification-by-Velocity-Threshold (IVT) algorithm which is described in slightly different ways in multiple publications (e.g. [1]).

Classification: In our context, classification means to label eye tracking data with the ID of a unique participant. As classifiers we use Random Decision Forests (RF) (as implemented in [2]) and Radial Basis Function Networks (RBFN) as described in [1].

Prediction Correctness Heatmap (PCH)

In Figure 1 we show the positive histograms for the Prediction Correctness Value (PCV) of each fixation from fixations and saccades.

In Figure 3 the PCV is shown for all trajectory segments of a participant reading a poem. The top row (a, b) shows results from the test cases with unseen data. We see that different algorithm perform similar and are highlighting the same areas as beneficial for the prediction (good to differentiate between participants). This leads to further research Questions about what makes this regions special e.g. are there specific words which are read very differently by the participants?/